



RAIL SYSTEMS ENGINEERING

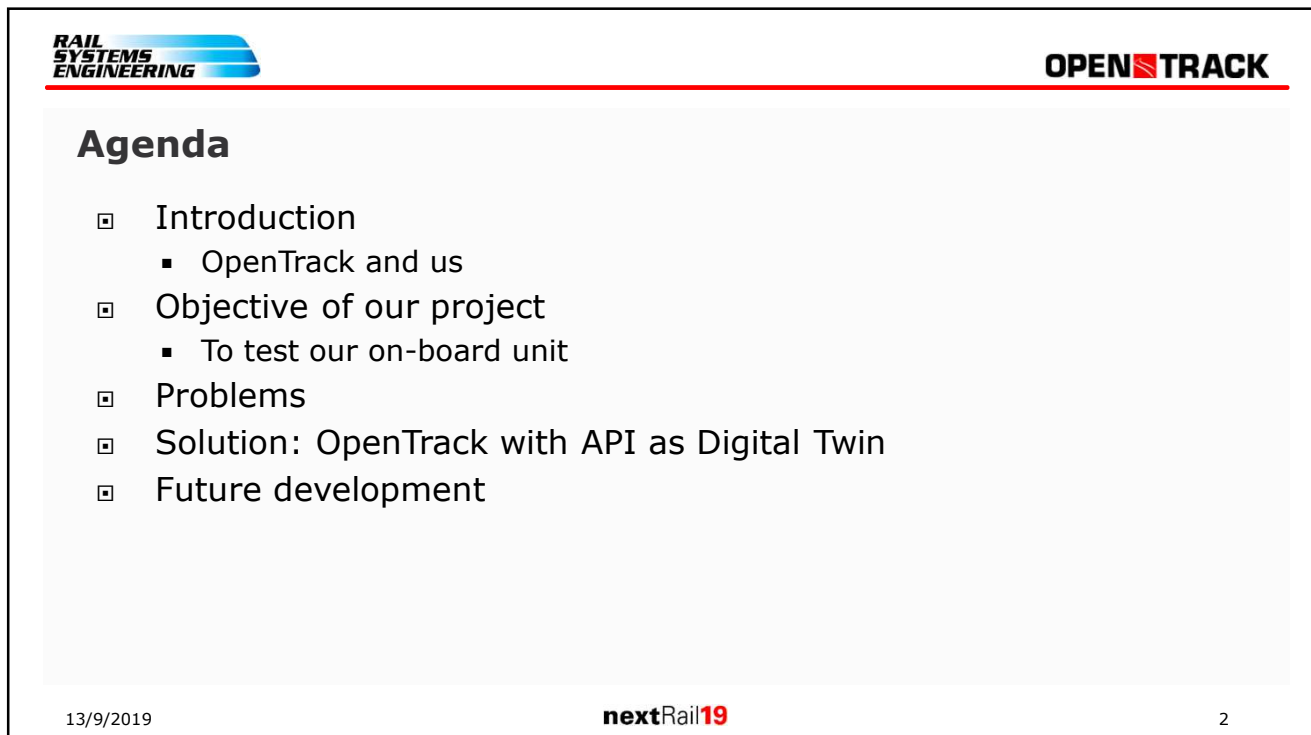
OPENTRACK

nextRail19

OpenTrack with API as Digital Twin in Industrial Product Development

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Agenda

- ▣ Introduction
 - OpenTrack and us
- ▣ Objective of our project
 - To test our on-board unit
- ▣ Problems
- ▣ Solution: OpenTrack with API as Digital Twin
- ▣ Future development

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Our companies


Rail Systems Engineering Sdn Bhd:

- ▣ Based and registered in Kuala Lumpur, Malaysia
- ▣ Founded in 2008
- ▣ Timetable, Simulations and Operations Consulting
- ▣ OpenTrack's representative for East Asia



Rail Systems Engineering AG:

- ▣ Based and registered in Wallisellen, Switzerland
- ▣ Founded in 2017
- ▣ ETCS, ATP and ATO



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About us

Philipp Goetz

- Founder and MD of "Rail Systems Engineering Sdn Bhd"
- Dipl. Eng. ETH Zurich
Master of Science in Electrical Engineering
- 26 years in Railway business
- Swiss, living in Malaysia for 19 years



DeeKeat ONG

- Railway Operation Simulation
- Dipl. Ing. ENSAM Lille
Master of Engineering in Mechanical Engineering
- Malaysian



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Our World with OpenTrack

- ▣ Malaysia
- ▣ Thailand
- ▣ ASEAN
- ▣ Taiwan
- ▣ South Korea

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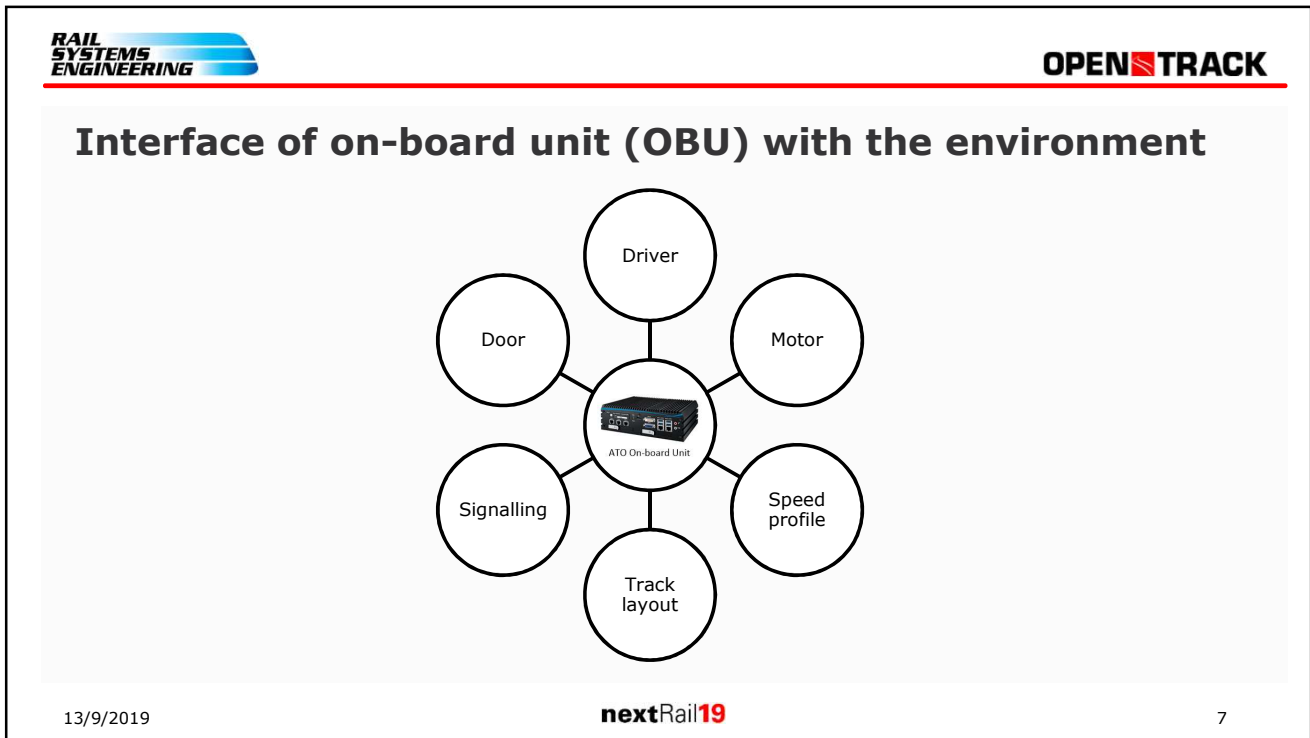
Objective of our project

- ▣ To develop an ATO computer and run it with a real train
 - E.g. controls the train's operation from starting until the next stop

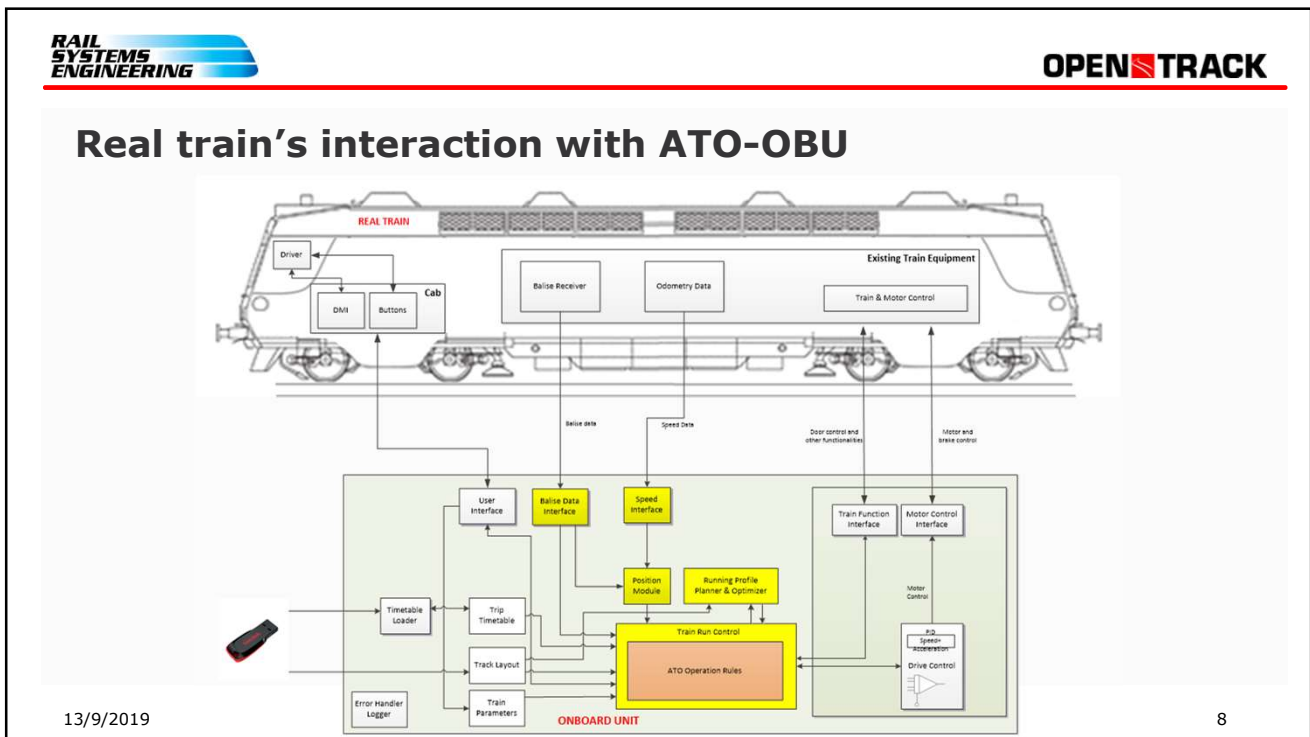
ATO On-board Unit → Train Control → Real Train

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Problems

To test the OBU, we need

- ▣ A driver
- ▣ A trainset (ready for testing)
- ▣ A timeslot
- ▣ Complete test team

+ many retrial runs → Expensive and time-consuming

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Solution: Create a Digital Twin to run with OT API

- ▣ Testing in the real world
 - Real train
 - Real track
 - Real driver
- ▣ Testing with a Digital Twin
 - OpenTrack is our reality
 - ▣ Itinerary
 - ▣ Track layout
 - ▣ Signalling
 - ▣ Rolling stock
 - The ATO On-board unit will not know the difference of real and Digital Twin world

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Our Solution using OpenTrack API:

- OpenTrack API principle

- Our application

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Our Test System's Setup

- Digital Twin's Software**
 - Our Software (.Net)
 - Data Interfaces
- Digital Twin's Hardware**
 - Test PC**
 - with OT and our own Digital Twin Software
 - Mini Cab (optional)**
 - with Buttons and indication as in a cab
 - ATO-OBU**
 - real hardware to be installed in the train

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Mini Cab

- ▣ Cab Train Driver Interface used for Digital Twin
- ▣ Buttons and indications as in the Cab
- ▣ Controlled with Arduino
- ▣ USB plug to Digital Twin PC



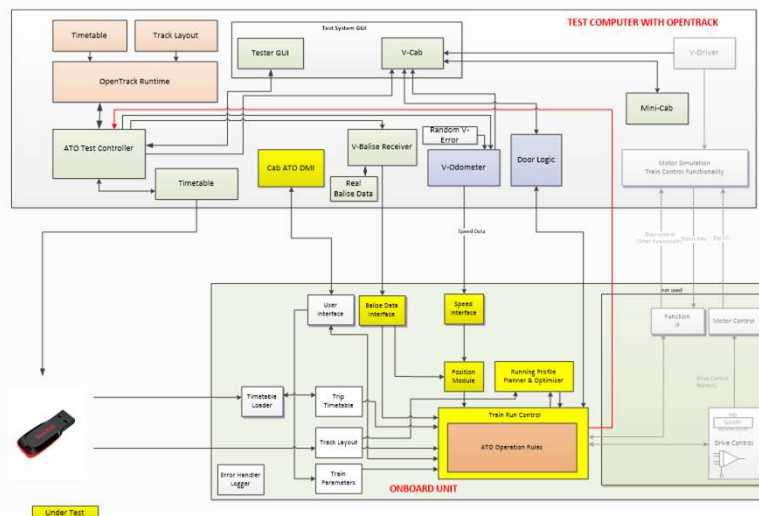
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Digital Twin interaction with ATO-OBU



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Things that we test

```
graph TD; A((To test)) --- B((Driver Interaction)); A --- C((Train runs)); A --- D((Interpretation of data)); A --- E((Incidents)); A --- F((Timetables)); A --- G((Optimisation));
```

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Things that we test

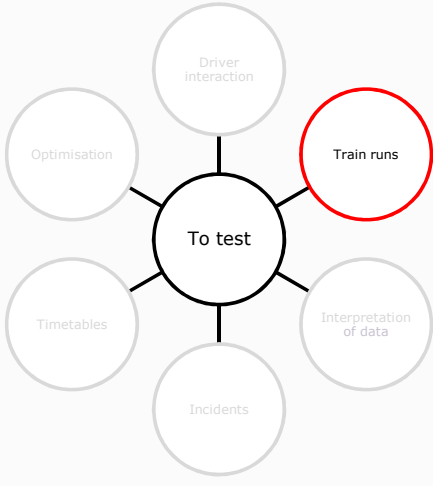
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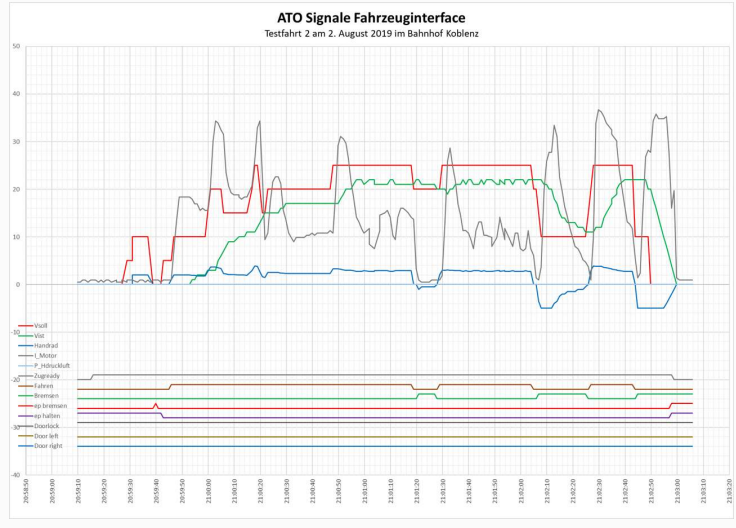
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Things that we test







ATO Signale Fahrzeuginterface
Testfahrt 2 am 2. August 2019 im Bahnhof Koblenz

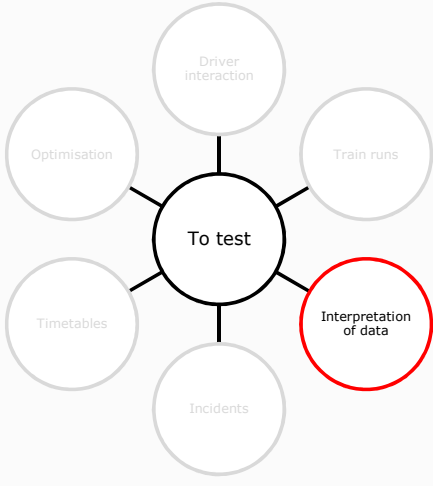
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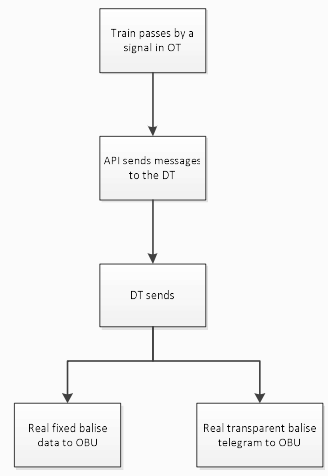
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Things that we test







```

graph TD
    A[Train passes by a signal in CT] --> B[API sends messages to the DT]
    B --> C[DT sends]
    C --> D[Real fixed balise data to OBU]
    C --> E[Real transparent balise telegram to OBU]
    
```

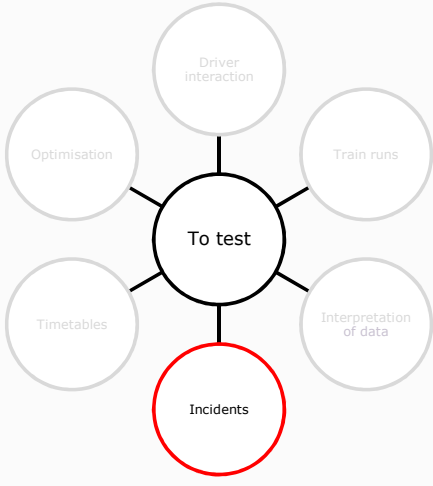
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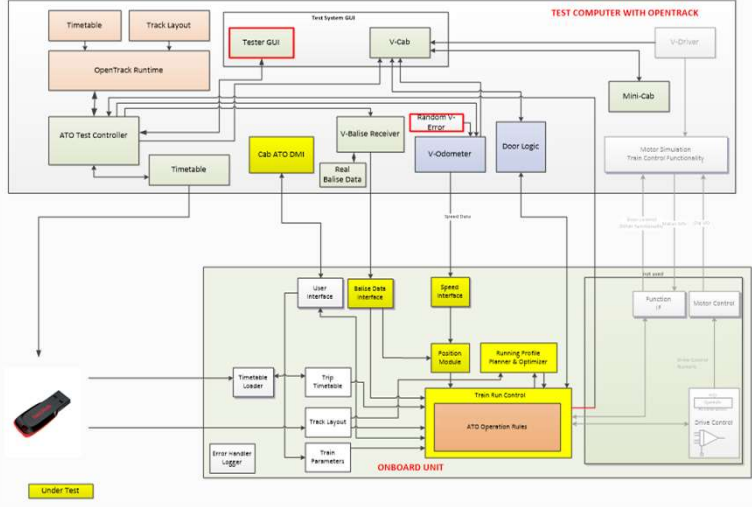
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Things that we test






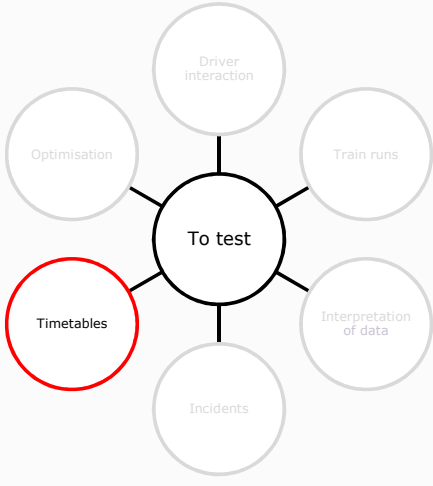
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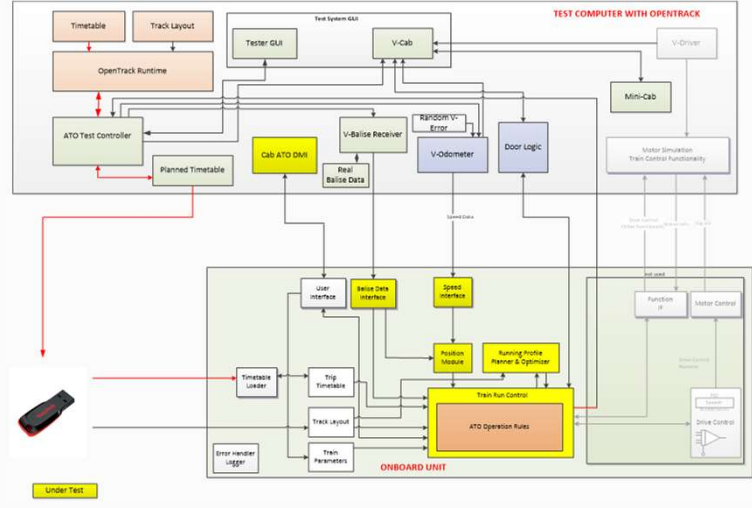
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Things that we test



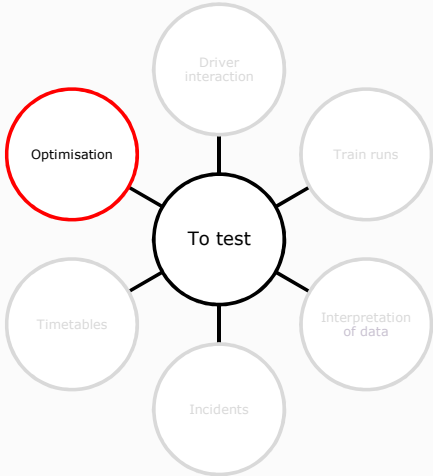


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Things that we test





OT API can run an optimised speed profile

- ▣ With coasting
- ▣ To catch up delays (higher acceleration/ target speed)

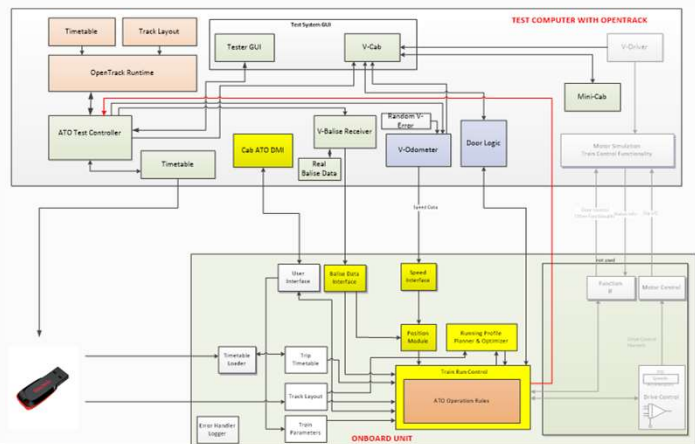
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Shortcuts taken in our solution

- ▣ The motor control is not considered
 - Motor control is verified separately



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Constant Improvement in OpenTrack API

- New functions for our DT
 - Balise telegram
 - showing signal aspect message of both main/distant signal in API
 - Train control
 - specifying maximum acceleration

```
graph TD; A[Train passes by a signal in OT] --> B[API sends messages to the DT]; B --> C[DT sends]; C --> D[Real fixed balise data to OBU]; C --> E[Real transparent balise telegram to OBU];
```

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Summary

- Our Task:
 - To develop and test a product used to control a train
- Our product:
 - An industrial computer (ATO-OBU) with interfaces with our own software
- Testing
 - Too complex

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Conclusion

- ▣ OpenTrack with API gives us all the control and info we need:
 - Simulation of running time (OT)
 - Real-time location and movement specific data (OT+API)
 - Control train run from "outside" (OT+API)

- ▣ **OpenTrack with API is the perfect tool to build a Digital Twin**